

Detection of thin inclusions in linear elasticity

Elisa Francini

Università di Firenze
in collaboration with Elena Beretta and others

AIP 2011

The direct problem

- 1 Asymptotic formula for displacement field in the presence of small volume inclusions
- 2 Thin inclusions in an elastic body

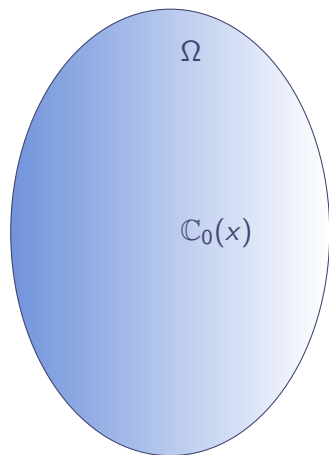
The inverse problem

- 1 The correction term: a crack model
- 2 Uniqueness
- 3 Stability
- 4 Reconstruction
- 5 Related problems

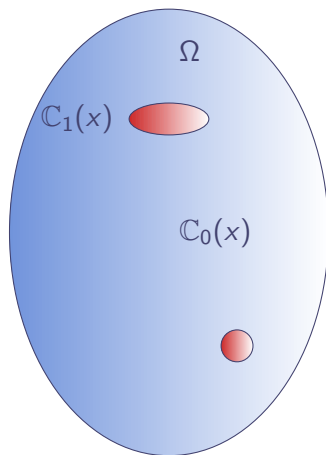
Part I

Small volume inclusions

Inclusions in an elastic body



Reference medium

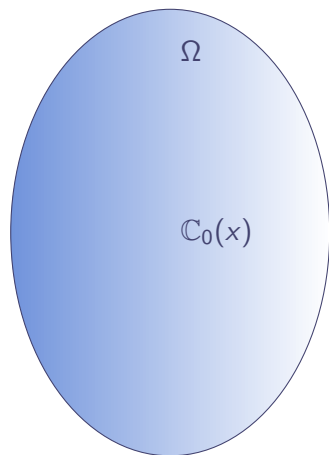


Perturbed medium

Setting:

The volume of the inclusion is small with respect to the volume of Ω

The reference displacement field



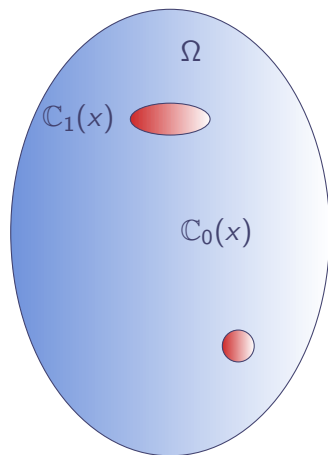
Reference medium

- $\Omega \subset \mathbb{R}^d$, $d \geq 2$ bounded, smooth.
- \mathbb{C}_0 be smooth, fully symmetric and strongly convex tensor.
- Background displacement field $u_0 \in \tilde{H}(\Omega, \mathbb{R}^d)$

$$\begin{cases} \operatorname{div}(\mathbb{C}_0 \widehat{\nabla} u_0) = 0 & \text{in } \Omega \\ (\mathbb{C}_0 \widehat{\nabla} u_0) \nu = \psi & \text{on } \partial\Omega, \end{cases}$$

where $\psi \in H^{-1/2}(\partial\Omega, \mathbb{R}^d)$ satisfies some compatibility condition

The perturbed displacement field



Perturbed medium

- ω_ϵ denotes the inclusion inside Ω .
- \mathbb{C}_1 elasticity tensor inside ω_ϵ , fully symmetric and strongly convex.

-

$$\mathbb{C}_\epsilon = \mathbb{C}_0 \chi_{\Omega \setminus \overline{\omega_\epsilon}} + \mathbb{C}_1 \chi_{\omega_\epsilon},$$

- perturbed displacement field:
 $u_\epsilon \in \tilde{H}(\Omega, \mathbb{R}^d)$ solution to

$$\begin{cases} \operatorname{div}(\mathbb{C}_\epsilon \widehat{\nabla} u_\epsilon) = 0 & \text{in } \Omega \\ (\mathbb{C}_\epsilon \widehat{\nabla} u_\epsilon) \nu = \psi & \text{on } \partial\Omega, \end{cases}$$

Assumptions and definitions

On the elasticity tensor

- $\mathbb{C}_0 \in C^{1,\alpha}(\Omega)$, $\mathbb{C}_1 \in C^\alpha(\Omega)$ are fully symmetric: for $m = 0, 1$
 $(\mathbb{C}_m(x))_{ijkl} = (\mathbb{C}_m(x))_{klij} = (\mathbb{C}_m(x))_{jikl}$, for $0 \leq i, j, k, l \leq d, x \in \Omega$.
- strongly convex: there is a positive number λ_0 such that
 $\mathbb{C}_m(x)A : A \geq \lambda_0 |A|^2$ for every $d \times d$ symmetric matrix A and $x \in \Omega$.

On the solution

- Compatibility condition on the Neumann datum $\psi \in H^{-1/2}(\partial\Omega, \mathbb{R}^d)$,
 $\int_{\partial\Omega} \psi \cdot R$ for every infinitesimal rigid motion R
- Normalization conditions:

$$\tilde{H}(\Omega, \mathbb{R}^d) = \left\{ u \in H^1(\Omega, \mathbb{R}^d) : \int_{\partial\Omega} u = 0, \int_{\Omega} \nabla u - (\nabla u)^T = 0 \right\}$$

The inclusions

Assume that

- ω_ϵ is measurable,
- $d(\omega_\epsilon, \partial\Omega) \geq d_0 > 0$
- $|\omega_\epsilon| > 0$ and $|\omega_\epsilon| \rightarrow 0$ as $\epsilon \rightarrow 0$

Strategy:

expand $u_\epsilon - u_0$ with respect to ϵ

Important ingredient

Neumann matrix for the background problem

$$\begin{cases} \operatorname{div}_x \left(\mathbb{C}_0 \hat{\nabla} N(x, y) \right) &= -\delta_y(x) I_d \quad \text{in } \Omega \\ (\mathbb{C}_0 \hat{\nabla} N) \nu &= -\frac{1}{|\partial\Omega|} I_d \quad \text{su } \partial\Omega, \\ \int_{\partial\Omega} N = 0, & \int_{\Omega} (\nabla N - \nabla N^T) = 0. \end{cases}$$

For existence and behaviour of N : M. FUCHS, *Manuscripta Math.*, 1984.

If $d = 2$ and \mathbb{C}_0 is a homogeneous isotropic elasticity tensor with Lamé constants λ_0, μ_0 ,

$$\Gamma_{ij}(x, y) := \frac{A}{2\pi} \delta_{ij} \ln |x - y| - \frac{B}{2\pi} \frac{(x - y)_i (x - y)_j}{|x - y|^2},$$

where $A = \frac{1}{2} \left(\frac{1}{\mu_0} + \frac{1}{\lambda_0 + 2\mu_0} \right)$ and $B = \frac{1}{2} \left(\frac{1}{\mu_0} - \frac{1}{\lambda_0 + 2\mu_0} \right)$

The asymptotic formula

Theorem

Let ω_{ϵ_j} be a sequence of measurable subsets of Ω such that $d(\omega_{\epsilon_j}, \partial\Omega) \geq d_0 > 0$ and, for $j \rightarrow \infty$,

$$|\omega_{\epsilon_j}| \rightarrow 0 \text{ and } |\omega_{\epsilon_j}|^{-1} \chi_{\omega_{\epsilon_j}} dx \rightarrow d\mu \text{ in the weak* topology of } (C(\overline{\Omega}))',$$

for some regular positive Borel measure μ , such that $\int_{\Omega} d\mu = 1$.

There exists a subsequence, not relabeled, and a fourth order tensor $\mathbb{M} \in L^2(\Omega, d\mu)$ such that

$$(u_{\epsilon_j} - u_0)(y) = |\omega_{\epsilon_j}| \int_{\Omega} \mathbb{M}(x) \widehat{\nabla} u_0(x) : \widehat{\nabla} N(x, y) d\mu_x + o(|\omega_{\epsilon_j}|),$$

for $y \in \partial\Omega$.

[E. BERETTA, E. BONNETIER, E.F., A.L. MAZZUCATO, preprint]

The scalar version of this result is contained in

[Y. CAPDEBOSCQ AND M. VOGELIUS, *A general representation formula for boundary voltage perturbations caused by internal conductivity inhomogeneities of low volume fraction*, *Math. Modeling Num. Anal.*, 2003.]

Some hints

Energy estimate

$$\|u_\epsilon - u_0\|_{H^1(\Omega)} \leq C|\omega_\epsilon|^{1/2}$$

and

$$\|u_\epsilon - u_0\|_{L^2(\Omega)} \leq C|\omega_\epsilon|^{1/2+\eta}$$

Correctors

The Elastic Moment Tensor \mathbb{M} is obtained as weak limit of

$$|\omega_\epsilon|^{-1} \chi_{\omega_\epsilon} (\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} v_\epsilon^{ij}$$

where $v_\epsilon^{ij} \in \tilde{H}(\Omega, \mathbb{R}^d)$ are solutions to

$$\begin{cases} \operatorname{div}(\mathbb{C}_\epsilon \widehat{\nabla} v_\epsilon^{ij}) &= \operatorname{div}(\mathbb{C}_0 e_i \otimes e_j) \text{ in } \Omega \\ (\mathbb{C}_\epsilon \widehat{\nabla} v_\epsilon^{ij})_\nu &= (\mathbb{C}_0 e_i \otimes e_j)_\nu \text{ on } \partial\Omega, \end{cases}$$

Properties of the Elastic Moment Tensor

Proposition

The Elastic Moment Tensor \mathbb{M} has the same symmetry properties of the elasticity tensors \mathbb{C}_0 and \mathbb{C}_1 , that is

$$\mathbb{M}_{ijkl} = \mathbb{M}_{klij} = \mathbb{M}_{jikl}, \quad \mu\text{-a.e.}$$

for any choice of indices i, j, k, l between 1 and d .

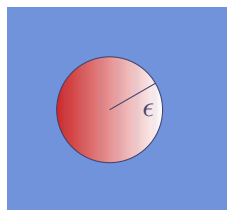
Moreover, for any symmetric matrix E ,

$$\mathbb{C}_0 \mathbb{C}_1^{-1} (\mathbb{C}_1 - \mathbb{C}_0) E : E \leq \mathbb{M} E : E \leq (\mathbb{C}_1 - \mathbb{C}_0) E : E \quad \mu\text{-a.e.}$$

Special geometries: diametrically small inclusions

$$\omega_\epsilon = \epsilon B, \quad B \text{ domain of measure } 1$$

$$|\omega_\epsilon| \approx \epsilon^d$$



References: homogeneous isotropic body

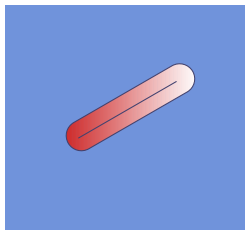
- H. AMMARI, H. KANG, G. NAKAMURA, AND K. TANUMA, *Complete asymptotic ...*, J. Elasticity, (2002).
- H. AMMARI AND H. KANG, *Reconstruction of Small Inhomogeneities from Boundary Measurements*, Lecture Notes in Math. 1846, Springer-Verlag, Berlin, 2004.
- H. AMMARI AND H. KANG, *Polarization and Moment Tensors: with Applications to Inverse Problems and Effective Medium Theory*, Applied Mathematical Sciences Series, Volume 162, Springer-Verlag, New York, 2007.

Special geometries: thin inclusions

$$\omega_\epsilon = \{x \in \Omega : d(x, \sigma) \leq \epsilon\},$$

for σ smooth non intersecting open curve in $\Omega \subset \mathbb{R}^2$

$$|\omega_\epsilon| \approx \epsilon$$



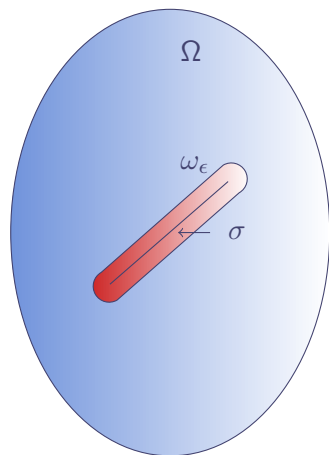
References

- (Isotropic inclusions) E. BERETTA AND E. F., *An asymptotic formula for the displacement field in the presence of thin elastic inhomogeneities*, SIAM J. Math. Anal., 38 (2006), 1249-1261.
- E. BERETTA, E. BONNETIER, E. F. AND A. L. MAZZUCATO, (2011) preprint.

Part II

Thin inclusions

Thin inclusions in a plane elastic body: isotropic homogeneous



$\Omega \subset \mathbb{R}^2$ is a plane region occupied by an elastic material containing an inclusion of the form

$$\omega_\epsilon = \{x \in \Omega : d(x, \sigma) < \epsilon\}$$

where σ is a line segment.

$$\mathbb{C}_\epsilon = \mathbb{C}_0 \chi_{\Omega \setminus \bar{\omega}_\epsilon} + \mathbb{C}_1 \chi_{\omega_\epsilon}$$

$$\{\mathbb{C}_m\}_{ijkl=1}^2 = \lambda_m \delta_{ij} \delta_{kl} + \mu_m (\delta_{ki} \delta_{lj} + \delta_{kj} \delta_{li})$$

Asymptotic formula

Theorem

For every $y \in \partial\Omega$ and for $\epsilon \rightarrow 0$

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_\sigma \mathbb{M}(x) \widehat{\nabla} u_0(x) : \widehat{\nabla} N(x, y) d\sigma(x) + o(\epsilon),$$

where

$$\mathbb{M} \widehat{\nabla} u_0 = a \operatorname{div} u_0 I_d + b \widehat{\nabla} u_0 + c \frac{\partial(u_0 \cdot \tau)}{\partial \tau} \tau \otimes \tau + d \frac{\partial(u_0 \cdot n)}{\partial n} n \otimes n,$$

where τ and n are the tangent and normal direction to segment σ and a , b , c , d , e and f depend only on the Lamé coefficients of \mathbb{C}_0 and \mathbb{C}_1 .

The term $o(\epsilon)$ is bounded by $C\epsilon^{1+\theta} \|\psi\|_{H^{-1/2}(\partial\Omega)}$, with $0 < \theta < 1$ and C depending only on Ω , α_0 , β_0 and K .

[E. BERETTA AND E. F., SIAM J. Math. Anal., 2006.]

The solution u_ϵ

Set $u_\epsilon^e := u_\epsilon|_{\Omega \setminus \overline{\omega_\epsilon}}$ and $u_\epsilon^i := u_\epsilon|_{\omega_\epsilon}$.

$$u_\epsilon^e \in C^{1,\alpha}(\Omega \setminus \omega_\epsilon) \text{ and } u_\epsilon^i \in C^{1,\alpha}(\overline{\omega_\epsilon}).$$

[Y.Y.LI AND L. NIRENBERG, Comm. Pure Appl. Math., 2003]

Equations:

$$\operatorname{div}(\mathbb{C}_0 \widehat{\nabla} u_\epsilon^e) = 0 \quad \text{in } \Omega \setminus \overline{\omega_\epsilon},$$

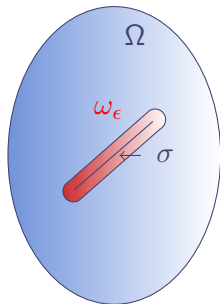
$$\operatorname{div}(\mathbb{C}_1 \widehat{\nabla} u_\epsilon^i) = 0 \quad \text{in } \omega_\epsilon.$$

Transmission conditions:

$$u_\epsilon^e = u_\epsilon^i \quad \text{su } \partial\omega_\epsilon,$$

$$(\mathbb{C}_0 \widehat{\nabla} u_\epsilon^e) n = (\mathbb{C}_1 \widehat{\nabla} u_\epsilon^i) n \quad \text{su } \partial\omega_\epsilon.$$

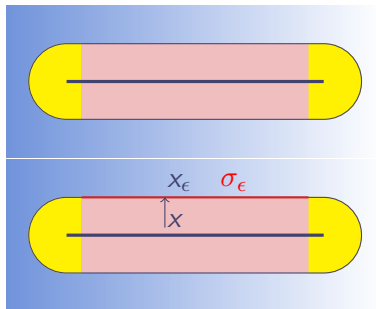
where n is the outer normal to $\partial\omega_\epsilon$,



Proof's main steps: localization to the boundary of the inclusion

- First, we show that $y \in \partial\Omega$,

$$(u_\epsilon - u_0)(y) = \int_{\omega_\epsilon} (\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} u_\epsilon^i(x) : \widehat{\nabla} N(x, y) dx.$$



- The yellow part of ω_ϵ gives a contribution of order $\epsilon^{1+\beta}$.



$$\nabla u_\epsilon^i \in C^\alpha(\overline{\omega_\epsilon^*})$$

$$\widehat{\nabla} u_\epsilon^i(x) \approx \widehat{\nabla} u_\epsilon^i(x_\epsilon)$$

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_{\sigma_\epsilon} (\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} u_\epsilon^i(x_\epsilon) : \widehat{\nabla} N(x_\epsilon, y) d\sigma_\epsilon + o(\epsilon).$$

Proof's main steps: outside the inclusion and final

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_{\sigma_\epsilon} (\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} u_\epsilon^i(x_\epsilon) : \widehat{\nabla} N(x_\epsilon, y) d\sigma_\epsilon + o(\epsilon).$$

We show that, there exists a tensor \mathbb{M} such that

$$(\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} u_\epsilon^i(x_\epsilon) = \mathbb{M} \widehat{\nabla} u_\epsilon^e$$

In the isotropic case, the existence of such a tensor \mathbb{M} follows immediately by the transmission conditions by solving a linear system.

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_{\sigma_\epsilon} \mathbb{M} \widehat{\nabla} u_\epsilon^e(x_\epsilon) : \widehat{\nabla} N(x_\epsilon, y) d\sigma_\epsilon + o(\epsilon).$$

Finally we show that

$$\|\nabla u_\epsilon^e - \nabla u_0\|_{L^\infty(\sigma_\epsilon)} \rightarrow 0$$

and get

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_{\sigma} \mathbb{M}(x) \widehat{\nabla} u_0(x) : \widehat{\nabla} N(x, y) d\sigma(x) + o(\epsilon),$$

An analogue asymptotic expansion holds true if σ is a regular curve or a collection of multiple disjoint curves.

More general elasticity tensor

This asymptotic expansion holds true if we can establish:

- Existence and local estimates for the Neumann matrix for background problem

[M. FUCHS, 1984]

- Interior regularity estimates for solutions.

[S. CAMPANATO, Quaderni della SNS di Pisa, 1980.]

Caccioppoli and Meyer's type inequalities for strongly convex systems with L^∞ coefficients.

- Existence of the Elastic Moment tensor such that

$$(\mathbb{C}_1 - \mathbb{C}_0) \widehat{\nabla} u_\epsilon^i = \mathbb{M} \widehat{\nabla} u_\epsilon^e$$

[G. A. FRANCFORT AND F. MURAT, *Homogenization and Optimal Bounds in Linear Elasticity*, *Arch. Rational Mech. Anal.*, 1986.]

Asymptotic expansion

Theorem

Let $\mathbb{C}_0 \in C^{1,\alpha}(\Omega)$ and $\mathbb{C}_1 \in C^1(\Omega)$ be fully symmetric and strongly convex tensors. For every $y \in \partial\Omega$ and for $\epsilon \rightarrow 0$

$$(u_\epsilon - u_0)(y) = 2\epsilon \int_{\sigma} \mathbb{M}(x) \widehat{\nabla} u_0(x) : \widehat{\nabla} N(x, y) d\sigma(x) + o(\epsilon),$$

where, for any symmetric matrix H ,

$$\mathbb{M}H = (\mathbb{C}_0 - \mathbb{C}_1)H + (\mathbb{C}_0 - \mathbb{C}_1)(q((\mathbb{C}_0 - \mathbb{C}_1)Hn) \otimes n).$$

Here q denotes the inverse of

$$(q^{-1}\zeta)\zeta = \mathbb{C}_1(\zeta \otimes n) : (\zeta \otimes n)$$

[E. BERETTA, E. BONNETIER, E. F., A.L. MAZZUCATO, preprint.]

Part III

The inverse problem

Thin inclusions: isotropic bodies

- E. Beretta, E. F. and S. Vessella *Determination of a linear crack in an elastic body from boundary measurements - Lipschitz Stability*, SIAM J. Math. Anal., 2006.
- E. Beretta, E. F., E. Kim and J.-Y. Lee *Algorithm for the determination of a linear crack in an elastic body from boundary measurements*, Inverse Problems, 2010.

The correction term

The asymptotic expansion gives:

$$(u_\epsilon - u_0)(y) = \epsilon u_\sigma(y) + o(\epsilon).$$

where

$$u_\sigma(y) = 2 \int_\sigma \mathbb{M}(x) \widehat{\nabla} u_0(x) : \widehat{\nabla} N(x, y) d\sigma(x)$$

is the first order approximation of u_ϵ that we will call **correction term**.

From now on we consider homogeneous isotropic strongly convex tensors with:

$$\mu_l \geq \alpha_0 > 0, \quad \lambda_l + \mu_l \geq \beta_0 > 0 \quad \text{for } l = 0, 1.$$

We also assume,

$$(\lambda_0 - \lambda_1)^2 + (\mu_0 - \mu_1)^2 > 0 \quad \text{and} \quad (\lambda_0 - \lambda_1)(\mu_0 - \mu_1) \geq 0.$$

The correction term

Consider a linear background

$$u_0(x) = Wx + c,$$

where W is a non zero symmetric matrix.

The function u_σ can be expressed in the following way

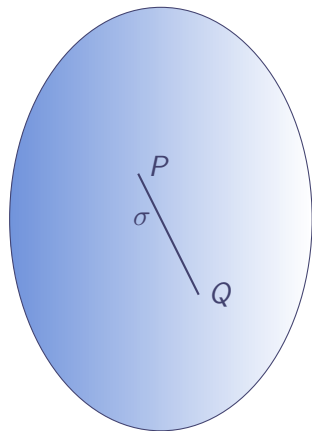
$$u_\sigma(y) = \int_\sigma \mathbb{C}_0 \widehat{\nabla} N(x, y) n \cdot \varphi d\sigma(x) + ((N(Q, y) \cdot \tau) - (N(P, y) \cdot \tau)) f.$$

Here

- P and Q are the endpoints of segment σ ,
- $\tau = \frac{PQ}{|PQ|}$ and $n = \tau^\perp$,
- φ is a vector valued function, f is a constant and they both depend only on W , on τ and n and on the Lamé coefficients.

The crack model

The correction term u_σ is the trace of a function that has the following properties:



- In $\Omega \setminus \sigma$ it solves the background system

$$\operatorname{div} \left(\mathbb{C}_0 \hat{\nabla} u_\sigma \right) = 0.$$

- At the endpoints $\{P, Q\}$ of the segment σ it has singularities proportional to $N(Q, y) \cdot \tau$ and $N(P, y) \cdot \tau$.
- It jumps across the segment σ .
- The correction term u_σ has a zero conormal derivative on $\partial\Omega$.

Problem:

Given the trace of the correction term on an open subset of $\partial\Omega$, determine the segment σ .

Proposition

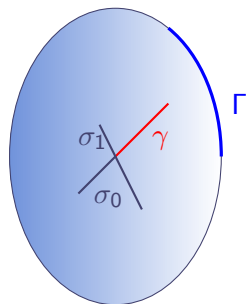
Let σ_0 and σ_1 be two segments contained in the interior of the open set Ω .
Let u_{σ_0} and u_{σ_1} be the correction terms corresponding to $\psi = (\mathbb{C}_0 W)\nu$.
Let Γ be an open subset of $\partial\Omega$. If

$$u_{\sigma_0} = u_{\sigma_1} \quad \text{on } \Gamma,$$

then

$$\sigma_0 = \sigma_1.$$

Sketch of proof



By unique continuation, since their Cauchy data coincide on Γ ,

$$u_{\sigma_0} = u_{\sigma_1} \quad \text{on} \quad \Omega \setminus (\sigma_0 \cup \sigma_1.)$$

If $\sigma_0 \neq \sigma_1$, there is a **part** γ of σ_0 not contained in σ_1 .

$\Rightarrow u_{\sigma_0}$ is bounded and has no jumps on γ .

$$u_{\sigma_0}(y) = \int_{\sigma_0} \mathbb{C}_0 \widehat{\nabla} N(x, y) n \cdot \varphi_0 \, d\sigma(x) + ((N(Q, y) \cdot \tau) - (N(P, y) \cdot \tau)) f_0.$$

But $\varphi_0 = 0$ and $f_0 = 0$ imply $W = 0$.

Theorem

Let σ_0 and σ_1 be two segments contained in Ω , far from the boundary and of positive length. Let u_{σ_0} and u_{σ_1} be the correction terms corresponding to $\psi = (\mathbb{C}_0 W)\nu$, and let Γ be an open subset of $\partial\Omega$.

There exists a constant C depending only on the a priori data such that

$$d_{\mathcal{H}}(\sigma_0, \sigma_1) \leq C \|u_{\sigma_0} - u_{\sigma_1}\|_{L^2(\Gamma)}.$$

where $d_{\mathcal{H}}$ denotes the Hausdorff distance.

[E. BERETTA, E. F., S. VESSELLA, SIAM J. Math. Anal., 2008]

Idea of the proof

Fix $u_0 = Wx + c$ non identically zero.

Let us define $T : \Lambda \subset \mathbb{R}^4 \rightarrow H^{1/2}(\Gamma)$ as the operator that associate to a segment σ the trace on Γ of u_σ .

We prove that, if we take K a compact subset of Λ , then:

- T is injective (uniqueness).
- T is Frèchet differentiable and its derivative is continuous and injective.

This implies that T^{-1} is continuous, hence, there is a constant C such that, taken two segments $\sigma_0, \sigma_1 \in K$, then

$$d_{\mathcal{H}}(\sigma_0, \sigma_1) \leq C \|u_{\sigma_0} - u_{\sigma_1}\|_{L^2(\Gamma)}.$$

Corollary

Let σ_0 and σ_1 be two segments contained in Ω , far from the boundary and of positive length and let Γ be an open subset of $\partial\Omega$.

For $j = 0, 1$, let u_ϵ^j be the solution of

$$\begin{cases} \operatorname{div}(\mathbb{C}_\epsilon \hat{\nabla} u_\epsilon^j) = 0 & \text{in } \Omega \\ (\mathbb{C}_\epsilon \hat{\nabla} u_\epsilon^j) \nu = g & \text{on } \partial\Omega, \end{cases}$$

corresponding to $\omega_\epsilon^j = \{x \in \Omega : d(x, \sigma_j) < \epsilon\}$.

Then, there exist a positive constant C and $\theta \in (0, 1)$, depending only on the a priori data, such that,

$$d_{\mathcal{H}}(\sigma_0, \sigma_1) \leq C \left(\epsilon^{-1} \|u_\epsilon^0 - u_\epsilon^1\|_{L^2(\Gamma)} + \epsilon^\theta \right).$$

Reconstruction: MELIR algorithm

[E. BERETTA, E. F., E. KIM AND J.-Y. LEE Inverse Problems, 2010]

$$u_\sigma(y) = \int_\sigma \mathbb{C}_0 \widehat{\nabla} N(x, y) n \cdot \varphi \, d\sigma(x) + ((N(Q, y) \cdot \tau) - (N(P, y) \cdot \tau)) f.$$

Idea:

there is a symmetric matrix W such that, for $\psi = (\mathbb{C}_0 W)\nu$,

$$u_\sigma^W(y) = (N(y, Q) - N(y, P)) \cdot \frac{Q - P}{|Q - P|}.$$

$(N(y, Q) - N(y, P)) \cdot \frac{Q - P}{|Q - P|}$ is in the range of $W \rightarrow u_\sigma^W$

Algorithm

Discretize:

We take Ω to be the unit disk centered at zero and choose N equi-spaced points y_i along the boundary $\partial\Omega$. Choose W_j , $j = 1, 2, 3$ a basis in the space of symmetric matrices, $\psi_j = (\mathbb{C}_0 W_j)\nu$.

Let $A := (u_\sigma^{W_j}(y_i))$ and consider its spectral decomposition

$$A = \sum_{p=1}^3 s^p u^p \otimes v^p.$$

Let $\mathbb{P} : \mathbb{R}^N \rightarrow \text{span}\{u^1, u^2, u^3\}$ be the orthogonal projector

$$\mathbb{P} = \sum_{p=1}^3 u^p \otimes u^p.$$

$$(I - \mathbb{P})(N(Q, y_i) - N(P, y_i)) \cdot \frac{Q - P}{|Q - P|} = 0.$$

Algorithm

Note that we cannot measure u_σ^W but $(u_\epsilon^W - u_0^W) = \epsilon u_\sigma^W + o(\epsilon)$

- Let $A_\epsilon := ((u_\epsilon^{W_j} - u_0^{W_j})(y_i))$. The $2N \times 3$ matrix A_ϵ has a spectral decomposition

$$A_\epsilon = \sum_{p=1}^3 s_\epsilon^p u_\epsilon^p \otimes v_\epsilon^p,$$

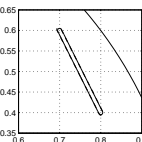
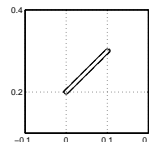
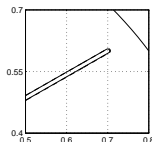
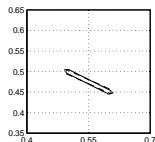
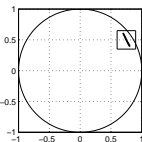
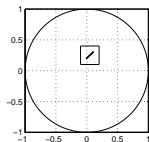
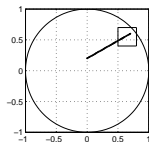
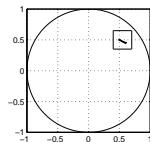
- Let $\mathbb{P}_\epsilon : \mathbb{R}^N \rightarrow \text{span}\{u_\epsilon^1, u_\epsilon^2, u_\epsilon^3\}$ be the orthogonal projector $\mathbb{P}_\epsilon = \sum_{p=1}^3 u_\epsilon^p \otimes u_\epsilon^p$.
- Compute P^c and Q^c that minimize

$$L(P, Q) := \frac{\|(I - \mathbb{P}_\epsilon)((N(Q, y_i) - N(P, y_i)) \cdot \tau)\|_{L^2(\partial\Omega)}}{\|\mathbb{P}_\epsilon((N(Q, y_i) - N(P, y_i)) \cdot \tau)\|_{L^2(\partial\Omega)}}$$

- Compute

$$\epsilon^c = \frac{\|u_\epsilon^W - u_0^W\|_{L^2(\partial\Omega)}}{\|u_{\sigma^c}^W\|_{L^2(\partial\Omega)}}.$$

Numerical experiments: MELIR algorithm

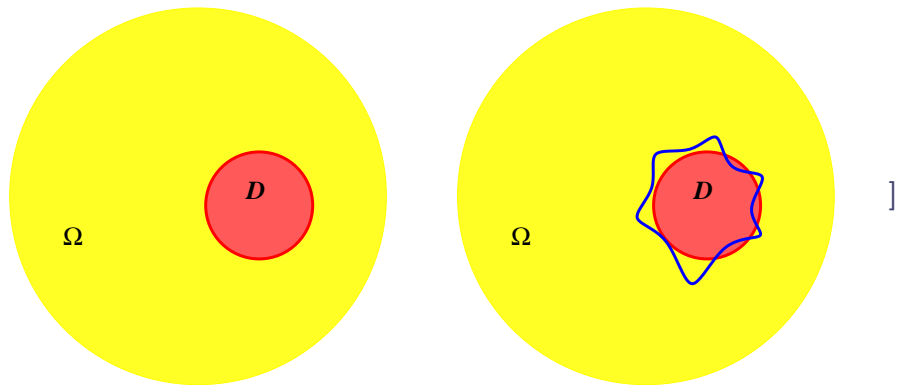


Case	P	Q	ϵ	$\frac{\ P - P^c\ }{\ P - Q\ }$	$\frac{\ Q - Q^c\ }{\ P - Q\ }$	$\frac{ \epsilon^c - \epsilon }{\epsilon}$	Err
1	(0.5,0.5)	(0.6,0.45)	5.0e-3	0.050	0.042	0.070	0.0964
2	(0.0,0.2)	(0.7,0.6)	5.0e-3	0.002	0.002	0.057	0.0574
3	(0.0,0.2)	(0.1,0.3)	5.0e-3	0.013	0.013	0.053	0.0558
4	(0.7,0.6)	(0.8,0.4)	5.0e-3	0.013	0.009	0.008	0.0178

Part IV

Small interface changes

Small perturbation of an interface

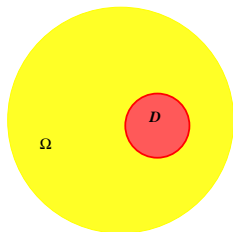


H. AMMARI, E. BERETTA, E. F., H. KANG, M. LIM, *Journal de Mathématiques Pures et Appliquées*, 2010.

Small perturbations of the elastic interface

$\Omega \subset \mathbb{R}^2$ is a planar region occupied by an elastic body containing an inclusion D of a different material.

Let \mathbb{C}_0 and \mathbb{C}_1 be the elastic tensor fields in $\Omega \setminus \overline{D}$ and D respectively.



We assume that both materials are isotropic and homogeneous with Lamé constants (λ_0, μ_0) and (λ_1, μ_1) .

Let u_0 be the solution of the following eigenvalue problem:

$$\begin{cases} \nabla \cdot (\mathbb{C}_D \widehat{\nabla} u_0) = -\omega_0^2 u_0 & \text{in } \Omega, \\ u_0 = 0 & \text{on } \partial\Omega, \\ \|u_0\|_{L^2(\Omega)} = 1, \end{cases}$$

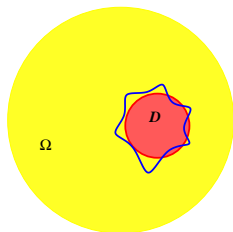
where $\mathbb{C}_D = \mathbb{C}_0 \mathbf{1}_{\Omega \setminus D} + \mathbb{C}_1 \mathbf{1}_D$.

The perturbed problem

Let

$$\partial D_\epsilon = \left\{ x + \epsilon h(x)\nu(x), x \in \partial D \right\},$$

$\nu(x)$ unit outer normal vector to ∂D at x ,
 h smooth function and ϵ positive small parameter.



$$\mathbb{C}_{D_\epsilon} = \mathbb{C}_0 \mathbf{1}_{\Omega \setminus D_\epsilon} + \mathbb{C}_1 \mathbf{1}_{D_\epsilon}$$

Let $u_\epsilon \in H^1(\Omega)$ be the solution to

$$\begin{cases} \nabla \cdot (\mathbb{C}_{D_\epsilon} \widehat{\nabla} u_\epsilon) = -\omega_\epsilon^2 u_\epsilon & \text{in } \Omega, \\ u_\epsilon = 0 & \text{on } \partial\Omega, \\ \|u_\epsilon\|_{L^2(\Omega)} = 1. \end{cases}$$

Then u_ϵ satisfies the transmission conditions across ∂D_ϵ .

Assumptions

- $d(D, \partial\Omega) \geq K$
- $\partial\Omega \in C^{1,1}$ and $\partial D \in C^{2,1}$
- $h \in C^{1,1}$ and $\|h\|_{C^{1,1}} \leq H$
- Strong convexity of \mathbb{C}_0 and \mathbb{C}_1 :

$$\min(\mu_0, \mu_1) \geq \alpha_0 > 0, \quad \min(2\lambda_0 + 2\mu_0, 2\lambda_1 + 2\mu_1) \geq \beta_0 > 0,$$

Asymptotic expansion of eigenvalue perturbation

Theorem

Let ω_0^2 be a simple eigenvalue. Then, there exists ω_ϵ^2 , such that $\omega_\epsilon^2 \rightarrow \omega_0^2$ as $\epsilon \rightarrow 0$ and

$$\omega_\epsilon^2 - \omega_0^2 = \epsilon \int_{\partial D} h(x) \mathbb{M} \widehat{\nabla} u_0^\epsilon(x) : \widehat{\nabla} u_0^\epsilon(x) d\sigma(x) + O(\epsilon^{1+\beta}),$$

for some positive β and where

$$\mathbb{M} \widehat{\nabla} u_0^\epsilon = a \operatorname{div} u_0^\epsilon I_d + b \widehat{\nabla} u_0 + c \frac{\partial(u_0^\epsilon \cdot \tau)}{\partial \tau} \tau \otimes \tau + d \frac{\partial(u_0^\epsilon \cdot n)}{\partial n} n \otimes n$$

where ν, τ are respectively the outward normal vector and the tangent vector to ∂D and a, b, c, d are constants depending on the Lamé coefficients .

- Osborn result on convergence of eigenvalues of sequences of self-adjoint collectively compact operators.
- Gradient estimates for solutions of elliptic systems (LI AND NIRENBERG and Meyer's type inequality for L^∞ strongly convex tensors.)

$$\omega_\epsilon^2 - \omega_0^2 = \epsilon \int_{\partial D} h(x) \mathbb{M} \widehat{\nabla} u_0^\epsilon(x) : \widehat{\nabla} u_0^\epsilon(x) d\sigma(x) + O(\epsilon^{1+\beta}),$$

Problem:

From knowledge of eigenvalues and boundary value of eigenfunctions we want to determine the perturbation ϵh

Dual asymptotic formula

Let u_0 be an eigenfunction of the unperturbed problem corresponding to ω_0^2 .

For $g \in L^2(\partial\Omega)$ such that $\int_{\partial\Omega} g \cdot (\mathbb{C}_D \widehat{\nabla} u_0) \nu = 0$, let w_g be the solution to

$$\begin{cases} \nabla \cdot (\mathbb{C}_D \widehat{\nabla} w_g) = -\omega_0^2 w_g & \text{in } \Omega, \\ w_g = g & \text{on } \partial\Omega. \end{cases}$$

Multiplying the equation for w_g by u_ϵ , by using the divergence theorem, we get

$$\int_{\partial\Omega} g \cdot \mathbb{C}_0(\widehat{\nabla} u_\epsilon - \widehat{\nabla} u_0) \nu + (\omega_\epsilon^2 - \omega_0^2) \int_{\Omega} w_g \cdot u_\epsilon = \int_{\Omega} (\mathbb{C}_{D_\epsilon} - \mathbb{C}_D) \widehat{\nabla} u_\epsilon : \widehat{\nabla} w_g.$$

Dual asymptotic formula

We now use

- Gradient estimates for u_ϵ and w_g
- The asymptotic expansion of the eigenvalues

$$\omega_\epsilon^2 - \omega_0^2 = O(\epsilon)$$

- L^2 estimates for $u_\epsilon - u_0$

$$\|u_\epsilon - u_0\|_{L^2(\Omega)} \leq C\epsilon^{\frac{1}{2}+\eta}$$

for some positive η

- Energy estimates and transmission conditions

Dual asymptotic formula

We derive

Theorem

$$\begin{aligned} & \int_{\partial\Omega} g \cdot \mathbb{C}_0(\widehat{\nabla} u_\epsilon - \widehat{\nabla} u_0)\nu + (\omega_\epsilon^2 - \omega_0^2) \int_{\Omega} w_g \cdot u_0 \\ &= \epsilon \int_{\partial D} h(x) \mathbb{M} \widehat{\nabla} u_0^\epsilon(x) : \widehat{\nabla} w_g^\epsilon(x) d\sigma(x) + O(\epsilon^{1+\beta}) \end{aligned}$$

for some $\beta > 0$.